

Protos II 4400(X) / Protos 3400(X) **Process Analysis System** 

User Manual Protos COMFF 3400(X)-085 **Communication Module** Communication Unit for FOUNDATION Fieldbus





Latest Product Information: www.knick.de

#### Returns

Please contact our Service Team before returning a defective device. Ship the <u>cleaned</u> device to the address you have been given.

If the device has been in contact with process medium, it must be decontaminated/disinfected before shipment. In this case, place a Declaration of Contamination in the consignment to prevent any risk to the health and safety of our service personnel. The declaration is available at:



https://www.knick-international.com/en/service/repairs/

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Please observe the applicable local or national regulations concerning the disposal of "waste electrical and electronic equipment".

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## **Intended Use**

The module is a communication unit for Foundation Fieldbus.

The COMFF 3400X-085 module is intended for operation in locations subject to explosion hazards which require equipment of Group II, device category 2(1), gas/dust.

### **Safety Instructions**

#### **Operation in Explosive Atmospheres: COMFF 3400X-085 Module**

The module is approved for operation in explosive atmospheres.

When installing the product in a hazardous location, observe the information in the supplements to the certificates and, if applicable, the relevant control drawings.

Observe all applicable local and national codes and standards for the installation of electrical equipment in explosive atmospheres. For orientation, please refer to IEC 60079-14, EU directives 2014/34/EU and 1999/92/EC (ATEX), NFPA 70 (NEC), ANSI/ISA-RP12.06.01.

### **A WARNING!** Possible impairment of explosion protection.

- Modules which have already been used shall be subjected to a professional routine test before they may be operated in another type of protection.
- Prior to commissioning, the operating company must verify the intrinsic safety in accordance with the installation regulations of IEC 60079-14 for the complete interconnection of all equipment involved, including the connecting cables.
- The interconnection of Ex and non-Ex modules (mixed assembly) is not permitted.
- In hazardous locations the device shall only be cleaned with a damp cloth to prevent electrostatic charging.

#### Maintenance

The Protos modules cannot be repaired by the user. For inquiries regarding module repair, please contact Knick Elektronische Messgeräte GmbH & Co. KG at www.knick.de.

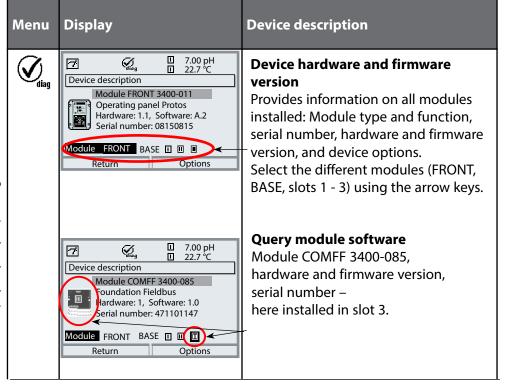
### **COMFF 3400(X)-085 module firmware:** Firmware version 2.x

Module compatibility	COMFF 3400-085	COMFF 3400X-085
Protos 3400 from FRONT firmware version 7.0	x	
Protos 3400X from FRONT firmware version 7.0		х
Protos II 4400 from FRONT firmware version 1.0.0	х	
Protos II 4400X from FRONT firmware version 1.0.0		х

#### **Query Current Device Firmware/Module Firmware**

When the device is in measuring mode:

Press **menu** key, open Diagnostics menu: Device Description



**Note:** The display may vary depending on the device version.

### Foundation Fieldbus (FF) Technology

Foundation Fieldbus (FF) is a digital communication system that connects different field devices over a common cable and integrates them into a control system. Its application range covers manufacturing, process, and building automation. As fieldbus standard according to EN 61158-2 (IEC 1158-2) the Foundation Fieldbus ensures the communication of different devices over one bus line.

#### **Basic Properties**

The "Data Link Layer" of the Fieldbus Foundation protocol defines 3 device types:

- The Active Link Master plans all activities as "Link Active Scheduler" (LAS).
   It controls the complete data traffic on the bus. Several Link Masters on one bus increase safety, but only one is active at a time.
- Basic devices are peripheral devices such as valves, drives, transmitters
  or analyzers. They can react acyclically to servicing, configuration and
  diagnostic tasks of the master. The Link Master cyclically reads the
  measurement data with status.
- Bridges can connect a network from different bus systems.

### Foundation Fieldbus (FF) Technology

#### **Bus Communication**

Foundation Fieldbus (FF) permits cyclic and acyclic services:

#### · Cyclic Services - Scheduled Communication:

are used for transmission of measurement data with status information. The Link Active Scheduler maintains a list of transmission times for all data in all devices that need to be cyclically transmitted. When it is time to transmit data, the LAS issues a "Compel Data (CD)" start signal to the respective device. Upon receipt of the "Compel Data" signal, the device broadcasts the data to all devices on the fieldbus.

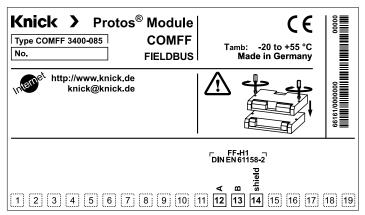
#### • Acyclic Services - Unscheduled Communication:

are used for device configuration, remote maintenance and diagnostics during operation.

All devices are given the chance to send acyclic (unscheduled) messages between transmissions of cyclic (scheduled) data. The LAS grants permission to a device to broadcast acyclic messages by issuing a "Pass Token (PT)" message. Upon receipt of the "Pass Token", the device starts data transmission.

### **Terminal Plate**

#### **Terminal Plate COMFF 3400-085 Module:**



#### **Attaching the Terminal Plates**

The terminal plates of the lower modules can be sticked to the inner side of the door.

This facilitates maintenance and service.



### **Installing the Module**

### **A** CAUTION! Electrostatic discharge (ESD).

The modules' signal inputs are sensitive to electrostatic discharge.

Take measures to protect against ESD before inserting the module and wiring the inputs.

**Note:** Strip the insulation from the wires using a suitable tool to prevent damage.



- 1) Switch off the power supply to the device.
- 2) Open the device (loosen the 4 screws on the front).
- 3) Plug the module into the slot (D-SUB connector), see figure.
- 4) Tighten the module's fastening screws.
- 5) Connect the signal lines (see next page).
- 6) Check whether all connections are correctly wired.
- 7) Close the device by tightening the screws on the front.
- 8) Switch on the power supply.

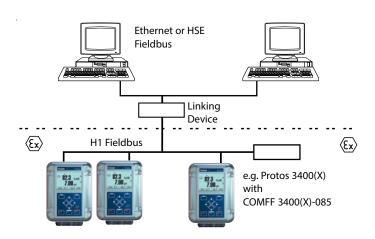
### **A** CAUTION! Incorrect measurement results.

Incorrect parameter setting, calibration or adjustment may result in incorrect measurements being recorded. Protos must therefore be commissioned by a system specialist, all its parameters must be set, and it must be fully adjusted.

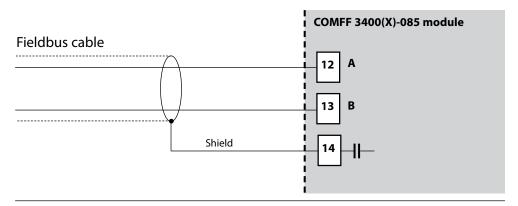
### **Foundation Fieldbus Installation**

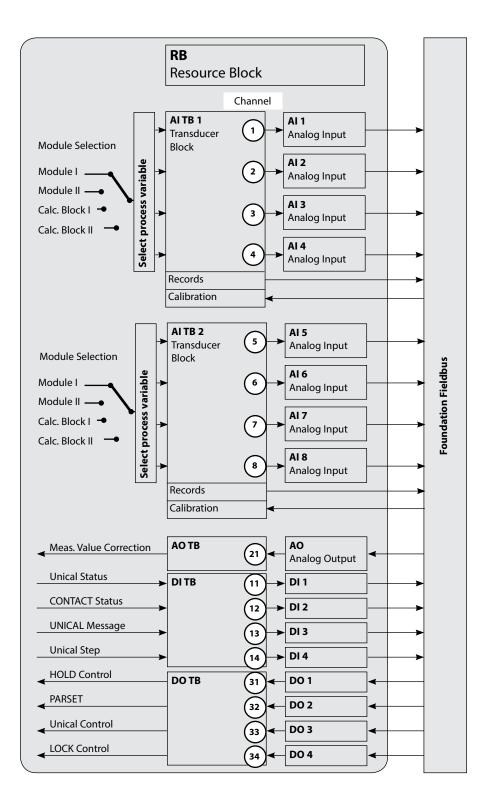
Basic build-up of a PROFIBUS system:

#### **Control room**



Electrical connection between module and Foundation Fieldbus is in accordance with FISCO (Fieldbus Intrinsically Safe Concept, www.fieldbus.org).





### **Communication Model**

See diagram on previous side

All variables and parameters of the transmitter are assigned to blocks.

#### **Resource Block (RB)**

Describes the transmitter characteristics (manufacturer, device name, operating status, general status).

#### **Analog Input Block (AI)**

2 x 4 Analog Input Function Blocks provide for cyclic transmission of measured values (currently measured value with status, alarm limits, freely selectable process variable from up to 2 measuring modules).

#### **Analog Input Transducer Block (AITB)**

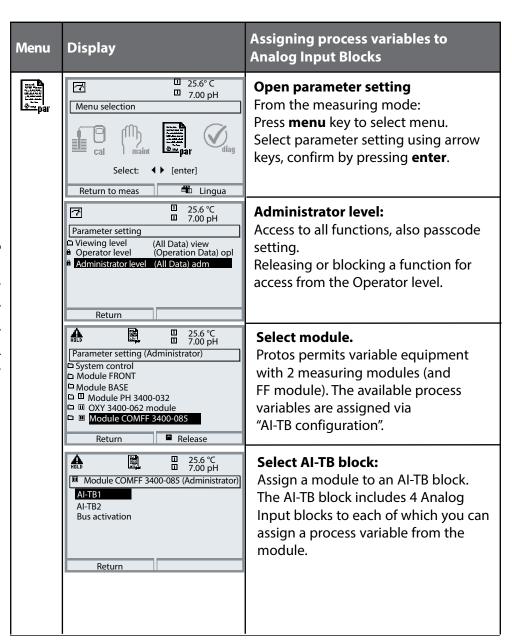
Provides for acyclic data transmission. Calibration, configuration, and maintenance commands coming from the control station are processed in the Transducer Block. The sensor signal is first preprocessed in the Transducer Block. From here, the measured value is sent to the Analog Input Blocks where it can be further processed (limit values, scaling).

#### **Connections (Channels)**

The communication model shows the channel numbers for connecting the function blocks to the Transducer Blocks.

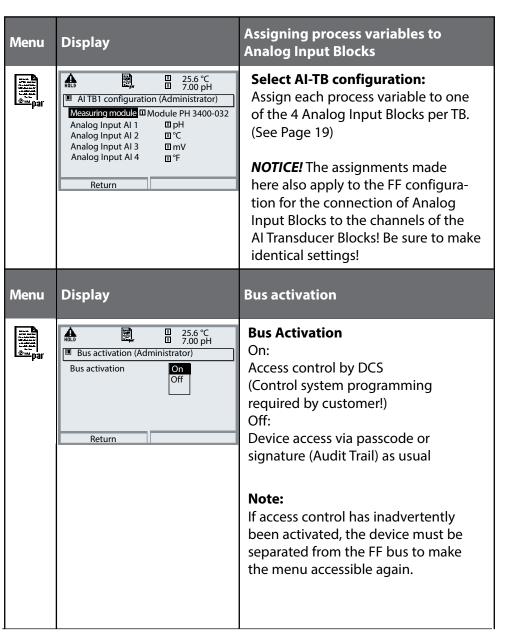
### AI-TB Configuration on the Device

Assigning process variables to Analog Input Blocks on the device



### **AI-TB Configuration on the Device**

Assigning process variables to Analog Input Blocks on the device



## For Copy: Individual Settings

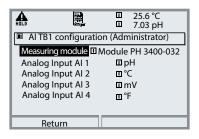
Assigning process variables to Analog Input Blocks on the device

AI-TB1 Selected measuring module  Analog Input Block AI 1  Analog Input Block AI 2  Analog Input Block AI 3  Analog Input Block AI 4  AI-TB2 Selected measuring module  Analog Input Block AI 5
Analog Input Block AI 2  Analog Input Block AI 3  Analog Input Block AI 4  AI-TB2 Selected measuring module  Analog Input Block AI 5
Analog Input Block AI 3  Analog Input Block AI 4  AI-TB2 Selected measuring module  Analog Input Block AI 5
Analog Input Block AI 4  AI-TB2 Selected measuring module  Analog Input Block AI 5
AI-TB2 Selected measuring module  Analog Input Block AI 5
Analog Input Block AI 5
Analog Imput Diogle ALC
Analog Input Block AI 6
Analog Input Block AI 7
Analog Input Block AI 8

### **Offline Configuration**

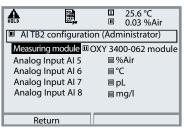
The AI blocks are divided into two groups (AI Transducer Blocks) which are each assigned to one measuring module. This allows control of functions in the measuring modules. If there is only one measuring module, both AI TBs can be assigned to the same module so that they can output more measured values cyclically. In this exemplary configuration there is a PH 3400-032 module in slot [I], an OXY 3400-062 module in slot [II], and the COMFF 3400-085 module in slot [III].

You can assign individual process variables from the selected measuring module to the different Al channels.



#### Example 1:

AI-TB1 is assigned to the pH 3400-032 module, therefore all process variables of the pH module are available for AI1 to AI4.



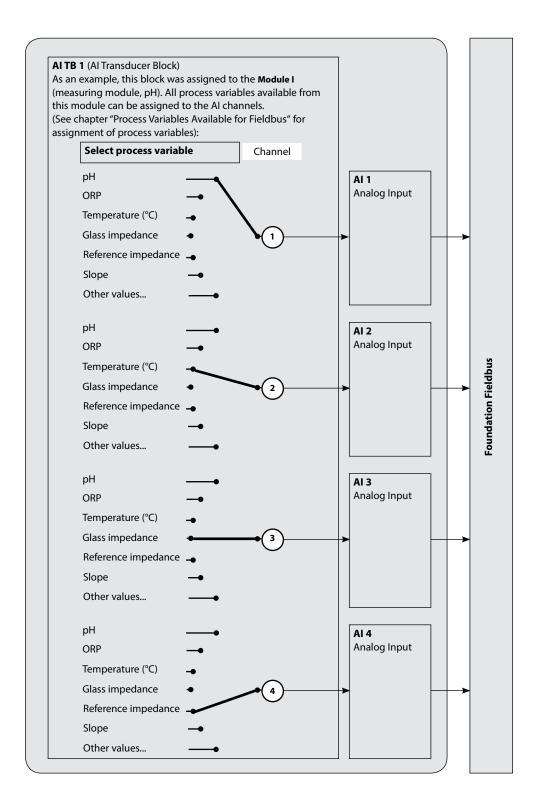
#### Example 2:

AI-TB2 is assigned to the OXY 3400-062 module,

therefore all process variables of the Oxy module are available for AI5 to AI8.

Bus communication on the Foundation Fieldbus can only function properly when during online configuration the blocks in the control system are set in accordance with the AI-TB configurations selected in the device configuration. The modular Protos does not allow permanent assignment of process variables to AIs - any available module can be located in one of the three slots, which cannot be recognized from the control system.

Therefore you cannot preconfigure the device offline per DD from the control system.



#### **Initial Commissioning**

- 1. Supply the device with power.
- 2. Open the configuration program of the control system.
- Load CFF file and DD.After the first connection establishment, the device answers as follows:

Device ID	COMFF 3400-085	0000000000001020D48	0000000000

4. Assign the desired name (PD\_TAG) to the field device.

#### **Setting the Resource Block (RB) parameters**

5. Set the MODE\_BLK. TARGET to Auto.

#### Setting the Analog Input Block (AI) parameters

- 6. Set MODE\_BLK. TARGET to OOS (Out Of Service).
- 7. Select the desired process variable from the CHANNEL parameter (Observe parameter setting of FRONT module!).
- 8. Select the unit belonging to the process variable from the XD\_SCALE parameter.
- 9. Select the unit belonging to the process variable from the OUT\_SCALE parameter.
- 10. Set the LIN\_TYPE linearization type to Direct and transmit the changes.
- 11. If these steps are not properly executed, the "Block Configuration Error" is generated when the block is set to "Auto".
  Using the NI-FBUS Configurator from National Instruments, for example, you can graphically connect the function blocks and then load the system configuration in the device.
- 12. Download all data and parameters to the field device.
- 13. Set the target modes of all Analog Input Blocks to "Auto".

### **Analog Input Blocks**

#### **Analog Input Blocks**

The module provides 8 analog input blocks (Al 1 ... Al 8).

An Analog Input Block contains the signal processing options for the process variable supplied from the Transducer Block.

The following parameters are available:

#### **Example:**

In the Protos AI 1 is set to pH value, AI 2 is set to temperature:

#### **Settings in Al 1:**

Parameter	Value
CHANNEL	Module 1 – Channel 1 (pH)
XD_SCALE, UNITS_INDEX	рН
OUT_SCALE, UNITS_INDEX	рН
L_TYPE	Direct
MODE_BLK, ACTUAL	Auto

#### **Settings in Al 2:**

Parameter	Value
CHANNEL	Module 1 – Channel 2 (°C)
XD_SCALE, UNITS_INDEX	°C
OUT_SCALE, UNITS_INDEX	°C
L_TYPE	Direct
MODE_BLK, ACTUAL	Auto

#### **NOTICE!**

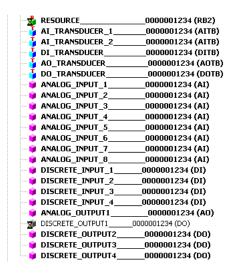
When connecting the AIs to the AI TBs, you must select the process variable (measurement unit) corresponding to the measured value selected in the Protos (see Page 15).

A faulty setting causes a Block Configuration Error in the AI function block.

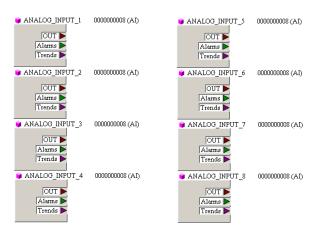
## **Configuration of AITB**

(Example: Configuration via NI-FBUS Configurator / National Instruments)

After connection of the Protos COMFF 3400-085 module to the Foundation Fieldbus the NI-FBUS Configurator shows this block overview (default setting: Fieldbus address 22)



Move all required Al blocks to the Function Block Application and start <u>Download Configuration</u>.



### **Configuration with Foundation Fieldbus**

#### **Commissioning on the Foundation Fieldbus**

Only when the COMFF 3400-085 module is competently configured, can the Foundation Fieldbus communication function properly. Different configuration tools from different manufacturers are available (e.g. NI-FBUS Configurator / National Instruments). They can be used to configure the device and the Foundation Fieldbus.

#### Note:

Be sure to observe the operating instructions and the menu guidance of the control system or the configuration tool during installation and configuration via the control system.

#### Installing the DD (Device Description):

During initial installation the device description (\*.cff, \*.sym and \*.ffo) must be installed in the control system.

For network projecting, you require the CFF file (Common File Format).

These files can be obtained from:

- the included CD
- internet: www.knick.de
- · Foundation Fieldbus: www.fieldbus.org.

#### **Identifying the Transmitter**

There are several possibilities to identify a FF transmitter in the network. The most important one is the "Device Identifier" or DEV\_ID. It consists of the manufacturer ID, device type and serial number of the transmitter.

Corresponding to example given on Page 18, "Offline Configuration"

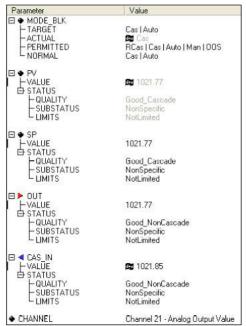
For parameter changes, you must set MODE\_BLK/TARGET to OOS (Out of Service) since otherwise the error message NIF\_ERR\_WRONG\_MODE\_FOR\_REQUEST would appear for [Write Changes].

Analog_Input_1		
"Process" card:	CHANNEL	Module 1 - Channel 1
"Scaling" card:	XD_SCALE/UNITS_INDEX	рН
	OUT_SCALE/UNITS_INDEX	рН
	L_TYPE	Direct
Button	[Write Changes]	
Button	[Auto]	
Analog_Input_2		
"Process" card:	CHANNEL	Module 1 - Channel 2
"Scaling" card:	XD_SCALE/UNITS_INDEX	°C
	OUT_SCALE/UNITS_INDEX	°C
	L_TYPE	Direct
Button	on [Write Changes]	
Button	[Auto]	
Analog_Input_3		
"Process" card:	CHANNEL	Module 1 - Channel 3
"Scaling" card:	XD_SCALE/UNITS_INDEX	mV
	OUT_SCALE/UNITS_INDEX	mV
	L_TYPE	Direct
Button	[Write Changes]	
Button	[Auto]	
Analog_Input_4		
"Process" card:	CHANNEL	Module 1 - Channel 4
"Scaling" card:	XD_SCALE/UNITS_INDEX	Mohm
	OUT_SCALE/UNITS_INDEX	Mohm
	L_TYPE	Direct
Button	[Write Changes]	
Button	[Auto]	

Analog_Input_5		
"Process" card:	CHANNEL	Module 2 - Channel 1
"Scaling" card:	XD_SCALE/UNITS_INDEX	%
	OUT_SCALE/UNITS_INDEX	%
	L_TYPE	Direct
Button	[Write Changes]	
Button	[Auto]	
Analog_Input_6		
"Process" card:	CHANNEL	Module 2 - Channel 2
"Scaling" card:	XD_SCALE/UNITS_INDEX	°C
	OUT_SCALE/UNITS_INDEX	°C
	L_TYPE	Direct
Button	[Write Changes]	
Button	[Auto]	
Analog_Input_7		
"Process" card:	CHANNEL	Module 2 - Channel 3
"Scaling" card:	XD_SCALE/UNITS_INDEX	mbar
	OUT_SCALE/UNITS_INDEX	mbar
	L_TYPE	Direct
Button	[Write Changes]	
Button	[Auto]	
Analog_Input_8		
"Process" card:	CHANNEL	Module 2 - Channel 4
"Scaling" card:	XD_SCALE/UNITS_INDEX	g/l
	OUT_SCALE/UNITS_INDEX	g/l
	L_TYPE	Direct
Button	[Write Changes]	
Button	[Auto]	

An external pressure sensor can be connected to the Analog Output Block (AO) through the Foundation Fieldbus network.

Analog_Output1		
"Process" card:	CHANNEL	Channel 21
		(Analog Output Value)
"Scaling" card:	XD_SCALE/EU_100	9999
	XD_SCALE/UNITS_INDEX	mbar
	OUT_SCALE/EU_100	9999
	OUT_SCALE/UNITS_INDEX	mbar
"Limits" card	SP_HI_LIM	9999
Button	[Write Changes]	
Button	[Cascade]	



Then the AO Block should be in ACTUAL Mode Cas.

The coupled output value (AI) from the linked pressure transmitter appears at input CAS\_IN.

In Cascade mode the measured OUT value is passed to the transmitter and is available to the system.

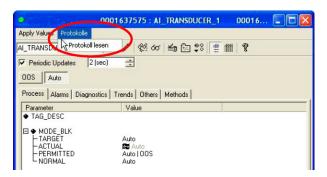
The parameter settings required for the DI and DO blocks are given on the following page.

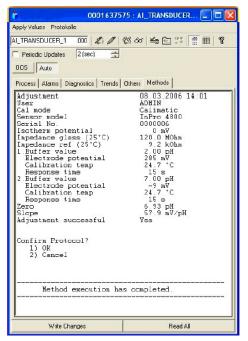
Discrete_Input_1			
"Process" card:	CHANNEL	Channel 11	Discrete Input Value
Button	[Write Changes]		
Button	[Auto]		
Discrete_Input_2			
"Process" card:	CHANNEL	Channel 12	Discrete Input Value
Button	[Write Changes]		
Button	[Auto]		
Discrete_Input_3			
"Process" card:	CHANNEL	Channel 13	Discrete Input Value
Button	[Write Changes]		
Button	[Auto]		
Discrete_Input_4			
"Process" card:	CHANNEL	Channel 14	Discrete Input Value
Button	[Write Changes]		
Button	[Auto]		
Discrete_Output1			
"Process" card:	CHANNEL	Channel 31	Discrete Output Value
Button	[Write Changes]		<u>'</u>
Button	[Auto]		
Discrete_Output2			
"Process" card:	CHANNEL	Channel 32	Discrete Output Value
Button	[Write Changes]		
Button	[Auto]		
Discrete_Output3			
"Process" card:	CHANNEL	Channel 33	Discrete Output Value
Button	[Write Changes]		
Button	[Auto]		
Discrete_Output4			
"Process" card:	CHANNEL	Channel 34	Discrete Output Value
Button	[Write Changes]		
Button	[Auto]		

### **Calibration Protocols**

#### **Calibration Protocols**

The protocols are transmitted in the AI TBs in binary form. The DD provides a method for converting them to a readable format. The method can be started with "Read protocol" in the "Protocol" menu of the AI TB.





Each AITB of the FF module has a ring buffer which can store up to three protocols. A fourth protocol would overwrite the first protocol in that TB. With "Read protocol", the calibration protocol of the respective module can be read out from the ALTB. The example shows the pH protocol of AI TB1. At the end of the method you can confirm the protocol (OK) and thus delete it from the ring buffer. After confirmation you will be informed if further data, i.e. another protocol, are available. Without confirmation (Cancel), you can re-read the protocol as often as you like.

### **Parameters of AI Transducer Blocks**

All blocks correspond to the "FF-007-5.0 Specifications". Only the two Al-TB blocks have been extended (Index 14 ... 39). Al-TB1 and Al-TB2 can be assigned to different measuring modules in the Protos.

Index	Parameter	Description
	Standard parameters	
0	AITB	
1	ST_REV	
2	TAG_DESC	
3	STRATEGY	
4	ALERT_KEY	
5	MODE_BLK	
6	BLOCK_ERR	
7	UPDATE_EVT	
8	BLOCK_ALM	
9	TRANSDUCER_DIRECTORY	
10	TRANSDUCER_TYPE	
11	XD_ERROR	
12	COLLECTION_DIRECTORY	
13	PRIMARY_VALUE	Measured value channel 1
	Manufacturer-specific extension	s: Measured values
14	SECONDARY_VALUE	Measured value channel 2
15	THIRD_VALUE	Measured value channel 3
16	FOURTH_VALUE	Measured value channel 4
	Manufacturer-specific extensions: Product calibration	
17	CAL_SAMPLE_PRD	Starts the first part of product calibration
18	CAL_SAMPLE_PRD_STORED_VAL	Shows the value stored during the first part of product calibration
19	CAL_PRODUCT	Sets the value for the second part of product calibration
20	CAL_MODE_PRD	"Mode of calibration"
21	CAL_RESULT	Result of calibration

### **Parameters of AI Transducer Blocks**

Index	Parameter	Description
	Manufacturer-specific extension	s: Protocols
22	PROTOCOL_STATUS	Status
23	PROTOCOL_DATA_0	Binary protocol data, part 1
24	PROTOCOL_DATA_1	
25	PROTOCOL_DATA_2	
26	PROTOCOL_DATA_3	
27	PROTOCOL_DATA_4	
28	PROTOCOL_DATA_5	
29	PROTOCOL_DATA_6	
30	PROTOCOL_DATA_7	
31	PROTOCOL_DATA_8	
32	PROTOCOL_DATA_9	
33	PROTOCOL_DATA_A	
34	PROTOCOL_DATA_B	
35	PROTOCOL_DATA_C	
36	PROTOCOL_DATA_D	
37	PROTOCOL_DATA_E	
38	PROTOCOL_DATA_F	Binary protocol data, part 16
39	PROTOCOL_CONFIRM	Save protocol

A ring buffer for up to 3 protocols is implemented in the module The DD includes a method for presenting the protocol in a readable manner. This method is called in the "Protocol" menu of the ALTB Block.

#### **Function Block AO**

Cyclic transmission of an external correction value (e.g. pressure correction for OXY 3400-062).

## **DI Function Blocks**

#### **DI 1: Unical Status**

Bit								Meaning
7	6	5	4	3	2	1	0	
							1	Probe in MEASURE position (PROCESS)
						1		Probe in SERVICE position
					1			Service switch actuated
				1				Unical alarm
			1					Unical program active
0	0	0						No program
0	0	1						Program: Cleaning
0	1	0						Program: Cal 2point
0	1	1						Program: Cal 1point
1	0	0						Program: Parking
1	0	1						Program: USER 1
1	1	0						Program: USER 2
1	1	1						Program: Service

### DI 2: CONTACTS / LOCK Status / ENABLE Request

Bit								Meaning
7	6	5	4	3	2	1	0	
							1	Contact K4 active
						1		Contact K3 active
					1			Contact K2 active
				1				Contact K1 active
			1					CAL terminates Al-TB1 (1 min or until cal record collected)
		1						CAL terminates Al-TB2 (1 min or until cal record collected)
0	0							Measuring mode
0	1							Unconfirmed enable request
1	0							Confirmed enable request
1	1							Enable

## **DI Function Block Unical Messages**

Unical with Protos II 4400(X) from FRONT firmware version 02.xx.xx

#### **DI 3: Unical Messages**

Bit								Meaning
7	6	5	4	3	2	1	0	
							1	Probe maintenance request
						1		Media adapter maintenance request
					1			Unical basic device maintenance request
				1				Medium maintenance request
			1					Probe failure
		1						Media adapter failure
	1							Unical basic device failure
1								Calibration / Communication error

### **Explanation of Unical Messages: Maintenance Request**

Probe m	Probe maintenance request								
U 231	Probe move time MEASURE (PROCESS)								
U 234	Probe move time SERVICE								
U 232	Proble wear counter								
U 228	Probe cylinder untight								
Media adapter maintenance request									
U 190	Buffer I almost empty								
U 191	Buffer II almost empty								
U 192	Cleaner almost empty								
Mainten	ance request / Unical basic device								
U 233	Water pressure switch								
U 229	Sensor dismount guard defective								
U 235	Safety valve defective								
U 248	Water valve defective (electrical)								

Medium	Medium maintenance request								
U 241	Check water								
U 242	Check buffer I								
U 243	Check buffer II								
U 244	Check cleaner								
U 245	Check aux. valve I								
U 246	Check aux. valve II								

## **Unical Messages, Unical Step**

Unical with Protos II 4400(X) from FRONT firmware version 02.xx.xx

#### **Explanation of Unical Messages: Failure**

Probe fa	Probe failure							
U 230	Probe limit position MEASURE (PROCESS)							
U 227	Probe limit position SERVICE							
Media adapter failure								
U 194	Buffer I empty							
U 195	Buffer II empty							
U 196	Cleaner empty							
UNICAL basic device failure								
U 220	Compressed air switch							
U 225	Probe valve defective							
U 224	Unical flooded							
U 221	Sensor dismounted							
Calibrat	ion / Communication error							
U 251	Calibration error							
U 252	Communication error							

### **DI 4: Unical Step**

Bit								Meaning
7	6	5	4	3	2	1	0	
							1	System in SINGLE_STEP
		Х	Х	Х	Х	Х		Step 1 30
	0							Reserved
0								Reserved

The half-automated Unical program control in Single-Step Mode can only be activated and triggered from the Protos. Control via bus is not possible, however the Single-Step Mode can be watched.

## **DO Function Blocks**

#### **DO 1: HOLD Control**

Bit								Meaning
7	6	5	4	3	2	1	0	
							1	System HOLD
						0		Reserved
					0			Reserved
				0				Reserved
			0					Reserved
		0						Reserved
	0							Reserved
0	)							Reserved

#### **DO 2: PARSET**

Bit								Meaning
7	6	5	4	3	2	1	0	
							1	Parameter set B (internal)
				0	0	0		Parameter set not from card
				0	0	1		Parameter set 1 (card)
				0	1	0		Parameter set 2 (card)
				0	1	1		Parameter set 3 (card)
				1	0	0		Parameter set 4 (card)
				1	0	1		Parameter set 5 (card)
			0					Reserved
		0						Reserved
	0							Reserved
0								Reserved

## **DO Function Blocks**

#### **DO 3: Unical Control**

Bit								Meaning
7	6	5	4	3	2	1	0	
							Х	Reserved
						1		Probe in SERVICE position (MEASURE = 0)
					1			Manual, Time control Off (Auto, Time control On = 1)
				Х		•		Reserved
			Х					Reserved
0	0	0						No program start
0	0	1						Program: Cleaning
0	1	0						Program: Cal 2point
0	1	1						Program: Cal 1point
1	0	0						Program: Parking
1	0	1						Program: USER 1
1	1	0						Program: USER 2
1	1	1						No program start

#### **DO 4: LOCK Control**

Bit								Meaning
7	6	5	4	3	2	1	0	
						0	0	Measuring mode
						0	1	Enabled
						1	0	Busy
						1	1	Not used
					Х			Reserved
				Х				Reserved
			Х					Reserved
		Х						Reserved
	Х							Reserved
Χ								Reserved

### **Enable / Lock via DCS**

**NOTICE!** Control system programming required by customer

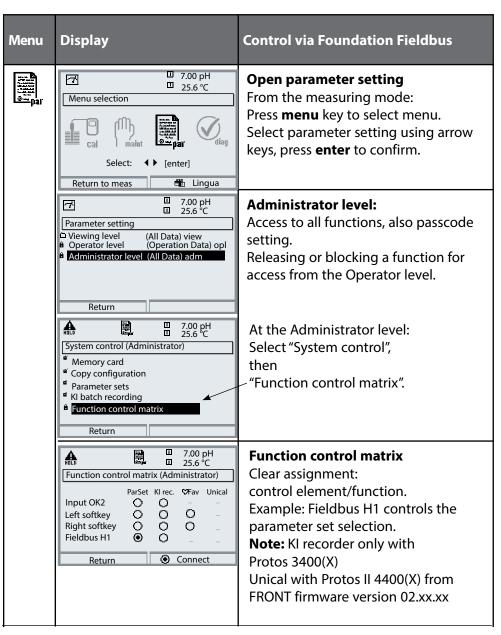
#### **Enable / Lock Protos for on-site calibration via DCS.**

The DI 1 and DO 4 function blocks are used for communicating with the DCS (control system programming required by customer).

Step 1:	The user calls the cal menu, for example, on the device. An "Enable request running" window appears instead of the passcode prompt. An enable request message is sent to the DCS.	
Step 2:	The DCS confirms the request, still without a decision. Now, a message window opens on the control system where the plant operator selects the decision Yes/No. Until a decision is made, the display reads "Wait for enable signal from DCS"	
Step 3:	The decision has been made:	
	YES:	The window disappears and the user is prompted to enter the passcode (or signature for AuditTrail). Now, he/she may use the menu.
	NO:	A "Request denied!" window appears and the device returns to measuring mode.
Step 4:	After the menu system has been exited, the DCS receives a message that manual operation is terminated. This erases the authorization.	

### **Function Control Matrix**

Controlling parameter set selection / KI recorder via Fieldbus H1
Parameter setting/Administrator level/System control/Function control matrix



# **Specifications**

### Protos COMFF 3400(X)-085

Foundation Fieldbus FF-H1	COMFF 3400X-085: Digital communication in hazardous areas via current modulation (Ex ia IIC)	
Physical interface	According to IEC 61158-2	
Transfer rate	31.25 kbits/s	
Communication protocol	FF-816	
Profile	FF_H1 (Foundation Fieldbus)	
Bus address	Visible on the device but not adjustable	
Supply voltage (FISCO)	Bus supply: 9 17.5 V Linear barrier: 9 24 V	
Current consumption	< 12 mA	
Max. current in case of fault (FDE)	< 17 mA	
FF communication model 1 Physical Block 5 transducer blocks 8 Al Function blocks 4 DI function blocks 4 DO Function blocks 1 AO function block	Certified to ITK 4.6 Device description Connection to signal processing Output of measured values with status via the Fieldbus Output of messages with status via the Fieldbus Control via the Fieldbus for analog compensation signals (e.g. O <sub>2</sub> process pressure)	

## **Specifications**

#### General data

(Ex version of module only)

See certificates or www.knick.de

**RoHS conformity** 

According to EU directive 2011/65/EU

**EMC** 

EN 61326-1, EN 61326-2-3

NAMUR NE 21

Emitted interference

Interference immunity Lightning protection

Industrial applications\* (EN 55011 Group 1 Class A)

Industrial applications

to EN 61000-4-5, Installation class 2

**Rated operating conditions** 

Ambient temperature:

Safe area: -20 ... 55 °C / -4 ... 131 °F

Ex: -20 ... 50 °C / -4 ... 122 °F

Relative humidity: 10 ... 95 % non-condensing

Transport/storage temperature

-20 ... 70 °C / -4 ... 158 °F

Screw clamp connector

Single or stranded wires up to 2.5 mm<sup>2</sup>

This equipment is not designed for domestic use, and is unable to guarantee adequate protection of the radio reception in such environments.

Process variables which can be assigned to Analog Input Blocks (AI):

### **pH Modules**

Measured value	Unit of measure
pH value	рН
Electrode voltage	mV
Electrode potential (ORP)	mV
rH value	rH
Glass impedance	Ohm
Reference impedance	Ohm
Temperature	°C
Temperature	°F
pH zero point	рН
pH slope	mV/pH

### Calculation Block pH / pH

Measured value	Unit of measure
Delta pH value	рН
Delta ORP	mV
Delta temperature	°C

Process variables which can be assigned to Analog Input Blocks (AI):

### O<sub>2</sub> Modules

Measured value	Unit of measure
Saturation (Air)	%
Saturation (O <sub>2</sub> )	%
Concentration	mg/l
Concentration	ppm
Volume concentration (GAS)	%
Volume concentration (GAS)	ppm
Sensor current	nA
Temperature	°C
Temperature	°F
Air pressure	mbar
O <sub>2</sub> partial pressure	mbar
Zero	nA
Slope	nA/mbar
Cal timer (adaptive)	h
Current input	mA

## Calculation Block ${\rm O_2}$ / ${\rm O_2}$

Unit of measure
%
%
°C
mg/l
ppm
%
ppm

Process variables which can be assigned to Analog Input Blocks (AI):

### **pH Modules**

Measured value	Unit of measure
Conductivity	μS/cm
Resistivity	Ohm/cm
Concentration	%
Concentration	g/kg
Temperature	°C
Temperature	°F
cell constant	cm <sup>-1</sup>
USP value	%

### **Calculation Block COND/COND**

Measured value	Unit of measure
Delta conductivity	μS/cm
Delta resistivity	Ohm/cm
Delta temperature	°C
Ratio	
Passage	%
Rejection	%
Deviation	%
pH value	рН

Process variables which can be assigned to Analog Input Blocks (AI):

### O<sub>2</sub> Modules

Measured value	Unit of measure
Conductivity	μS/cm
Resistivity	Ohm/cm
Concentration	%
Concentration	g/kg
Temperature	°C
Temperature	°F
Zero	S/cm
Cell factor	(value only)

### **Calculation Block CONDI / CONDI**

Measured value	Unit of measure
Delta conductivity	μS/cm
Delta resistivity	Ohm/cm
Delta temperature	°C
Ratio	
Passage	%
Rejection	%
Deviation	%

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